

Analysis of AC Solar Water Pump and PV array with Battery

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Abstract- Fossil fuel resources are permanently decreasing in quantity and their pollution to the environment is always increasing. Due to this problems, the new era led to use the renewable energies. These resources are not finished at all and have no dangers to the environment, animals and human lives. Due to these reasons, in this study we analyze a Photovoltaic (PV) powered centrifugal water pump scheme for water pumping in agricultural applications. The general system is connected to a battery to save the extra energy for the lackluster times. In this study, the utilized motor for driving the centrifugal pump is a three phase induction motor. Here, motor torque and speed depend on the frequency and source voltage, whereas the water-flow rate depends on the motor speed, static head and density according to the flow. The overall asynchrony pumping system fed by solar cell is simulated and the results are achieved.

Keywords: PV array, MPPT, Induction motor, water pumping, Centrifugal Pumps

INTRODUCTION

By developing the modern industrial society and population growth, the world energy demand is increased. This subject causes to make a great deal of investments in different energy solutions to enhance the energy performance and power quality problems.

One of these energy resources which has the considered cases is Photovoltaic (PV) energy resources. PVs are alternative and friendly to the environment energy resources. Photovoltaic energy resources provide a good solution to supply remote area with sustainable and clean energy during the daytime in lighting, heating, refrigeration and water pumps systems during the whole day and the night time (Q. Meng and W. Hu, 2005; Agrawal, 1989; Chikh et al., 2008).

Usually to set the output voltage of the photovoltaic with the inverter, a dc-dc converter is required. These converters can be boost or buck choppers in order to boost or unbrace the voltage to the predetermined levels.

The DC/DC choppers are mainly employed in regulated switch mode power supplies, where the input voltage of these converters changes in wide range especially in the Photovoltaic (PV) supply source due to sudden and unpredictable changes in the solar irradiation level like the cell operating temperature.

There are different connection topologies to concern the switching systems for the purpose of realizing the required voltage level during different periods of day for specific applications like motors, pumps in general and power supplies (Worrell et al., 2004; Kjaer et al., 2005; Odeh et al., 2006).

Generally, solar technology has two inherent problems: the presence of highly non-linear I-V characteristics and low conversion efficiency (10% to 16% efficiency for commercially available amorphous silicon solar cells).

The dependency of the solar system characteristics to the temperature and insolation level variations gets the issue worse. Hence, the maximum power point (MPP) and operating point of the solar cells get mismatch. To achieve the maximum power from the PV panel source, it should be capable to track the solar panel unique maximum power point which varies with temperature and irradiance. To do this, MPPT can be employed by using any one of the algorithms perturb & observe (P&O).

Water pumping system is one of the most popular applications of the photovoltaic energy utilization which is driven by electrical motors. One of the most and frequently encountered machines in industry is the three-phase induction motors. Their popularity is because of their high power, simple design and easy maintaining.

V/f control for induction motors has a big deal of applications in industry. The control purpose is to keep the voltage-frequency ratio of the motor supply source constant.

Subhankar et al. (2012) proposed a PID controller to a squirrel cage induction motor under constant volt/hertz ratio. In this study motor model is achieved based on the transfer function due to inductance matrices or L-matrices of the motor.

Dazhi et al. (2004) proposed a PID controller based on neural network for speed sensor less field-oriented control of induction motor. The neural networks based rotor flux components and speed identification method for IM are utilized by measuring the voltages and currents of the phase in Induction Motor (IM) drive.

Power electronics converters can be used to reduce the initial investments of the photovoltaic water pumping system and to adapt the electrical impedance to the PVG for different operating conditions dynamically (Matsui et al., 1999).

Various studies have been done on the choice of the drive system, which suits PVG, type of pumps to use and

In the past, only the DC motors were utilized to drive pumps. Some studies about direct coupling of shunt, series and separately excited DC motors in water pumping systems were studied (Appelbum, 1986; Saied, 1988, Fam and Balachander, 1988).

In this paper, we propose an efficient and simple photovoltaic water pumping system. We consider the theoretical studies of photovoltaics (PV) and their modeling methods. The maximum power point tracker (MPPT) is also investigated and a power electronic device is utilized to improve the system efficiency. Finally, simulation results of the system are given and analyzed.

Photovoltaic system (PV)

PV is a nonlinear system which can be modeled as a current source paralleled by a diode. The practical model of the photovoltaic cell is a serial and shunt connection of resistors (R_s and R_p) which can be mathematically modeled as below:

$$I = I_{pv} - Id - \left(\frac{V + IR_s}{R_p} \right) \tag{1}$$

where,

$$Id = I_0 \left[\exp \left(\frac{V_j q}{KT} \right) - 1 \right] \tag{2}$$

I is the voltaic output current, V is the voltaic output voltage, k is the bultsman constant ($1.3806503 \text{ e-}23\text{J K}^{-1}$), K is the diode ideal constant, I_0 is the diode inverse saturation current, q is the electron charge and T is the p-n junction temperature (Razmjooy et al., 2011). After that, the nonlinear I-V characteristics of the PV can be given as below:

$$V = V_t \ln \left(\frac{I_p - (1 + \frac{R_s}{R_p})I - \frac{V}{R_p}}{I_0} + 1 \right) - R_s I \tag{3}$$

here, V_t is the array heating voltage by N_s number of series cells and I_p is the generated current derived from the radiation in the nominal condition and:

$$V = \frac{KT}{q} \tag{4}$$

Buck regulator

In a buck regulator, the average output voltage value is less than the input voltage value. The circuit diagram of a buck converter with a power electronic MOSFET is shown in the fig.1. From the figure, it is obvious that the system is as similar as the step reduced chopper.

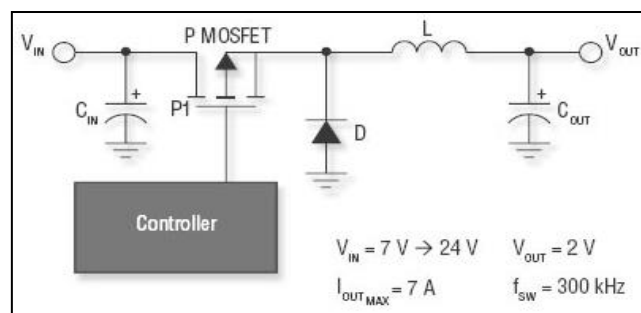


Figure 1. the main circuit of BUCK chopper

$$V_o = V_i \frac{1}{\frac{2LI_o}{D^2VT} + 1} \tag{5}$$

where, L is the inductance, T describes the time, I_o is the output current, D is the duty cycle and V_i and V_o are the input and the output voltages. The output of the buck converter in here is connected to an MPPT to provide the maximum power for the system.

Inverter

By the radiation of sun rise, photovoltaic module generates DC energy. But for most of applications, especially in this paper which an induction motor is set in the output, we need to perform a conversion on the output DC energy into the AC energy. This operation can be performed easily by the inverter. By using the transformers, switches and control circuits, DC current get converted into the AC current and can have any value of frequency and voltage.

PWM switching technique is employed to drive the inverter with a modulation index M and the ratio between the frequencies of the carrier and modulating waveforms P . Murphy and Turnbull (1985) proved that when a full bridge control and $P > 9$, the root mean square value of the fundamental motor voltage V_m can be considered as below:

$$V_m = \frac{MV}{\sqrt{2}} \tag{6}$$

Three phase induction motor

Three phase induction motor is the most popular motor in the industry. This motor is usually utilizing in the adjustable speed drives. The simple but tenacious design, cheap cost, low cost in maintaining and its easy connection to the three phase source are some of the good characteristics of these motors. In this paper, this type of machine is utilized because of the considerations above.

When the armature is supplied by a balanced 3-phase voltage, a rotating magnetic field is generated. The speed of rotation is the synchronous speed can be given by the following formula:

$$\omega_s = \frac{4\pi f_1}{p} \text{ rad / s} \tag{7}$$

$$n_s = \frac{120 f_1}{p} \text{ rpm,} \tag{8}$$

here f_1 describes the line frequency and p is the number of poles of the armature winding.

The angular speed of the rotor in rad/s can be defined by ω and the speed in rev/min (rpm) can be defined by n . The speed of the rotor relative to the field (slip speed) is equal to:

$$\text{Slip speed} = \omega_s - \omega \text{ (rad/s)} = n_s - n \text{ (rpm)} = s \omega_s \tag{9}$$

here, s defines the slip and can be achieved by the equation below:

$$s = \frac{\omega_s - \omega}{\omega_s} = \frac{n_s - n}{n_s} \tag{10}$$

The rotor frequency is, thus,

$$f_2 = s f_1 \tag{11}$$

The equivalent circuit of an induction motor is shown in the figure below:

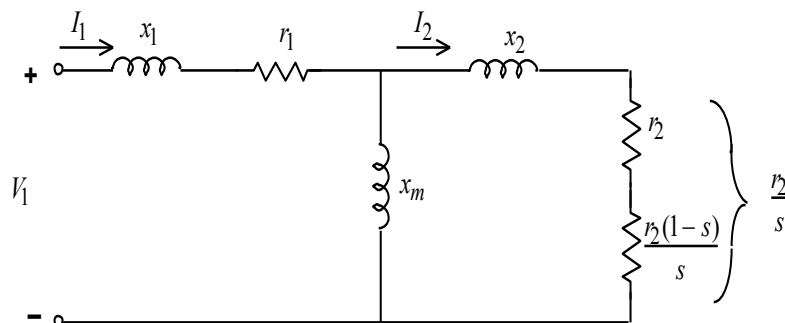


Figure 2. Equivalent Circuit of an Induction Motor

Simulation results

Out purpose in this paper is to use a PV system for free pumping the water in the agriculture lands especially for land that are Deprived. The novelty of our system is using battery and also utilizing renewable energy for pumping the water. The operation steps are operated as follows:

Instead of the fossil fuels, our system uses renewable energy. after receiving the illumination and generating the energy by the PV cells, a buck converter is used to reduce the voltage value into the range of inverter. The output voltage gets into an inverter to convert it into the AC current. The existence of the inverter in this paper is because of the existence of the induction motor in the output. After taking the output voltage from the inverter and performing it into the induction motor, for proper control of the induction motor, a PID technique is used. This type of the controller is a hybrid of proportional, integrator and derivative controllers which is widely utilized in the industry.

MATLAB-Simulink model of the PV system used in this study is shown in fig.5. The dc to dc buck converter is used to step down the dc voltage to the considered level and also to reduce the usage of PV modules.

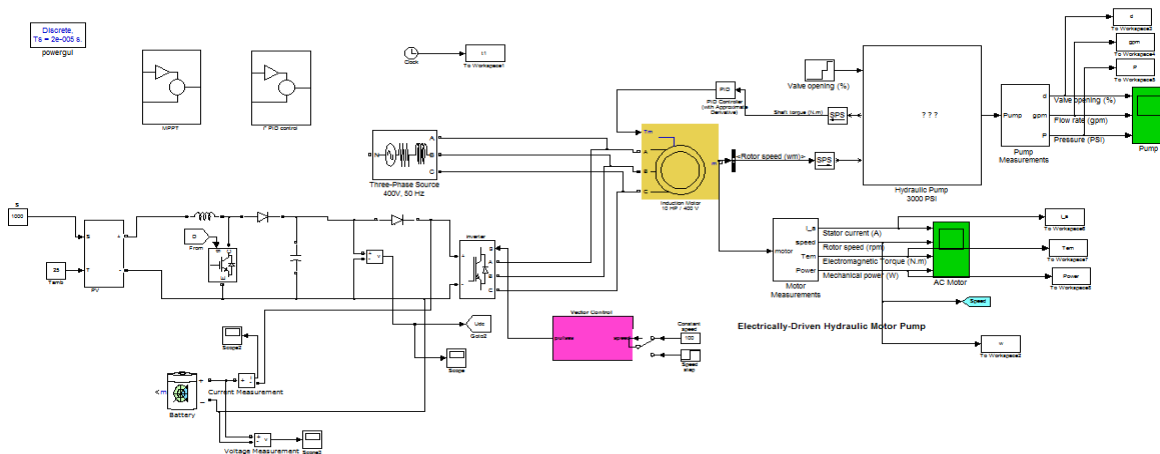


Figure 5. MATLAB-Simulink model of the PV system

The converter is designed for continuous inductor current mode with following specifications: $L=6000\mu\text{H}$, $C=1000\mu\text{F}$. The system characteristics of the module are shown in Table 1.

Table 1. Parameters of the proposed PV module

| Parameter | Variable | Value |
|--|----------|--|
| Maximum power | Pmpp | 40 W |
| Voltage at Pmax | Vmpp | 17.3 V |
| Current at Pmax | Impp | 2.31 A |
| Short-circuit current | ISC | 2.54 A |
| Open-circuit voltage | VOC | 21.8 V |
| Temperature coefficient of open-circuit voltage | Kv | $-(80\pm 10)\text{ mV}/^\circ\text{C}$ |
| Temperature coefficient of short-circuit current | Ki | $(0.065\pm 0.015)\%/^\circ\text{C}$ |

The power-voltage (PV) and current-voltage (IV) diagram of the photovoltaic array at the nominal condition is shown below in figures 6 and 7.

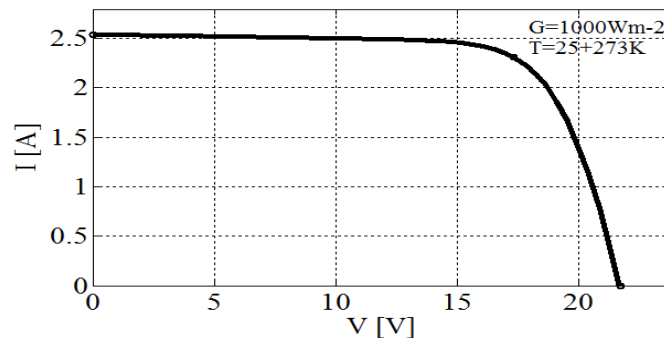


Figure 6. V-I diagram of the PV array in the nominal condition

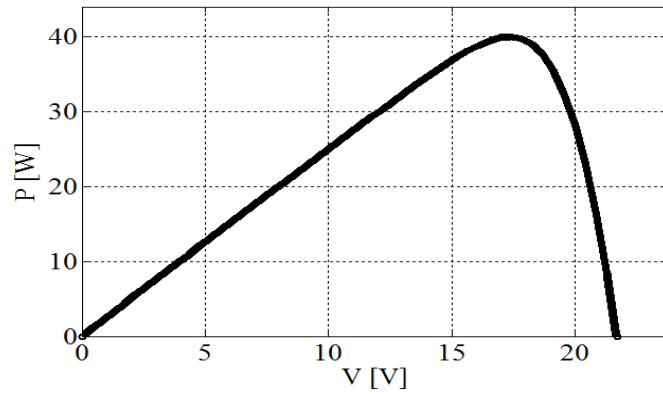


Figure 7. P-I diagram of the PV array in the nominal condition

The pump switching is shown in the fig.8. from the figure, the switching times are characterized based on time.

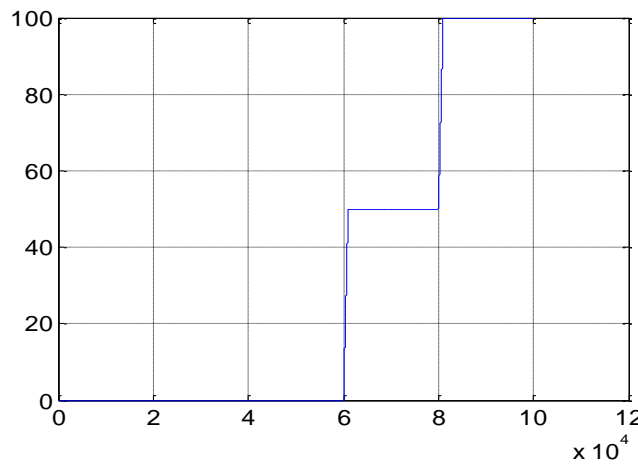


Figure 8. pump switching

The flow rate of the system is shown in figure below. As it can be seen, at first we have no flow rate till the battery get charged fully. After charging, the energy get performed to the induction motor and pump and make the flow rate get increased.

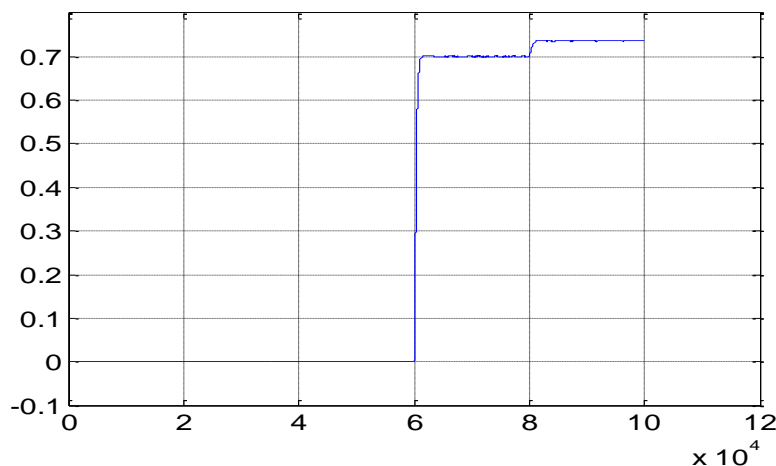


Figure 9. debi flow rate

By using the PID technique to control the induction motor torque, the output system is achieved as fig.10. note that, in this system, a PI controller achieved the considered purpose and there is no need to the derivative controller. The value for proportional and integrator controllers are: $K_p=1$, $K_i=3$ respectively.

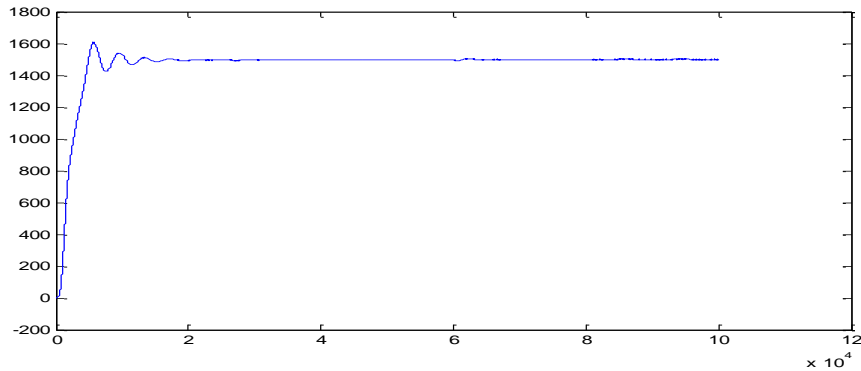


Figure 10. Step response of the induction motor torque

CONCLUSION

One of the advantages of the renewable energies toward the oil fuels is that they have no pollution to the environment. Furthermore, they can provide a free energy for using in any applications like agriculture. In this study, a photovoltaic powered centrifugal pump is presented. The achieved power required by the pump is delivered from the induction motor depending on the head and flow rate. For supplying the induction motor energy, an inverter is used in between the PV array and the induction motor. For enhancing the induction motor efficiency, a PID controller is performed on its torque. The simulation results are applied by MATLAB Simulink and the results show a good performance for the proposed system.

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